

Automated Transporting Solution

C-MATIC HP 10

Capacity 1.0t | Series 8928

Autonomous transport miracle

- ightarrow Autonomous transport solution for medium to long distances in mixed operations
- ightarrow Load capacity 1000 kg and maximum speed of 8 km/h for fast transfer of loads
- ightarrow Natural feature navigation for optimal orientation without additional infrastructure
- \rightarrow Independent avoidance of obstacles and flexible load pick-up for trouble-free process flows
- ightarrow Cloud-based software control for effortless implementation and optimum adjustment

TECHNICAL DATA (According to VDI 2198)

S	1.1 1.2	Manufacturer		Linde MH
tics		Model		C-MATIC HP 10
eris	1.2.a	Series		8928-01
Characteristics	1.3.	Power Unit		Battery
	1.4	Operation		Automated
	1.5	Load capacity/Load	Q (t)	1.0
	1.8	Axle centre to fork face	x (mm)	390
Weights	2.1	Service weight	(kg)	170 1)
es	3.1	Tyres rubber, SE, pneumatic, polyurethane		Vulkollan
Wheels / Tyres	3.4	Auxiliary wheels (dimensions)	(mm)	160 × 45
eels	3.5	Wheels, number front/rear (x = driven)	(Ø)	2x +2
ł	3.6	Track width, front	b10 (mm)	584
	4.4	Lift	h3 (mm)	40
	4.15	Height, lowered	h13 (mm)	222 2)
	4.16	Loading platform, length	l3 (mm)	1021 3)
Dimensions	4.18	Loading platform, width	b9 (mm)	619 4)
ensi	4.19	Overall length	l1 (mm)	1440
jü	4.21	Overall width	b1 (mm)	634
	4.33	Load dimension b12 × I6	b12 × l6 (mm)	860 × 1260
	4.34	Aisle width with predetermined load dimensions	Ast (mm)	2948 5)
	4.35	Turning radius	Wa (mm)	1592 6)
nce	5.1	Travel speed, with/without load	(m/s)	2.2
Performance	5.2	Lifting speed, with/without load	(m/s)	0.0203
Perf	5.3	Lowering speed, with/without load	(m/s)	0.0203
Drive	6.4	Battery voltage/rated capacity (5 h)	(V)/(Ah) o. (kWh)	48/120
Others	10.7	Sound pressure level LpAZ (at the driver's seat)	(dB(A))	< 70

1) Adaptor plate weight +45 kg

2) Adaptor plate +158 mm

3) Adaptor plate I3=1200

4) Adaptor plate b9=606

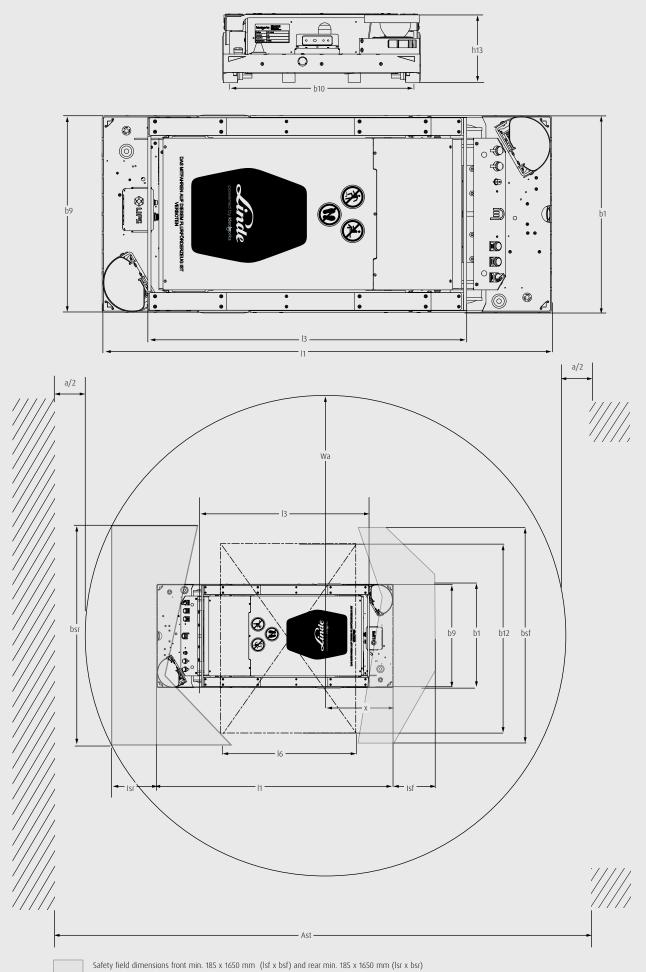
5) Including a=200 mm (min.) operating aisle clearance

High tolerance (+/-300 mm & +/-15°) 90° pick-up Ast=3669 mm With adaptor plate Ast=2857 mm

6) With adaptor plate and EPAL1 or EPAL3

(loaded 800, 1000 × 1200) Wa=1327 mm

C-MATIC HP 10



Ast = 2 * Wa + a, with a = 200 mm

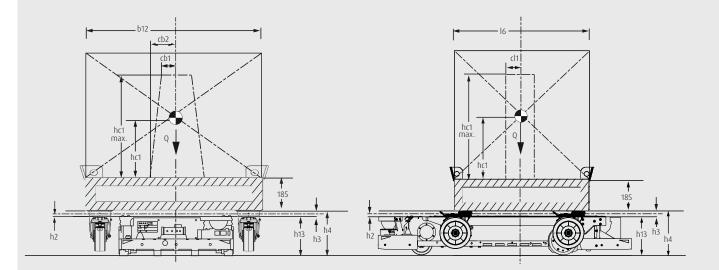
APPLICATION VARIANTS

Applications	Load carrier dimensions	Max. capacity	Overall height (lift lowered)	Lift	Overall height, max. extended
	l6 × b12 [x m2] (mm)	Q (kg)	h13 (mm)	h3 (mm)	h4 (mm)
Trolley transport	1260 × 860 x 235	1000	222	40	262
Direct pallet transport	1200 × 800 1200 × 1000	1000	380	40	420

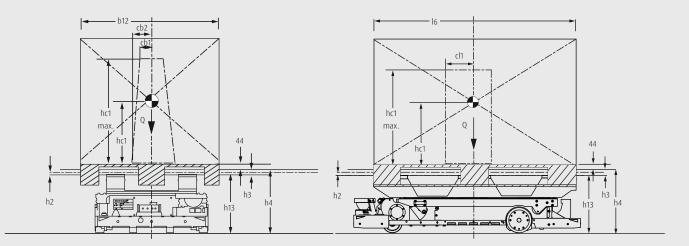
Vehicle variants	Entry height	Max height of CoG ²⁾	Max. displacement of CoG in main driving direction (I)		
	h13 + h2 ¹⁾ (mm)	hc1 (mm)	cl1 (mm)	cb1 (mm)	cb2 (mm)
Platform for trolley transport	235	800	30	60	80
Adaptor plate for direct pallet transport	400	800	30	60	80

1) h2 = free lift 2) CoG = Centre of Gravity

TROLLEY TRANSPORT

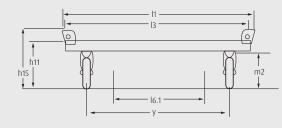


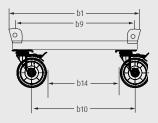
PALLET TRANSPORT



ADDITIONAL EQUIPMENT (TECHNICAL REQUIREMENTS)

TROLLEY TRANSPORT



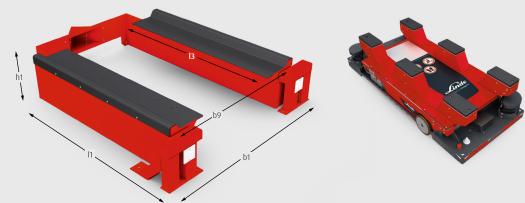


Characteristics	Trolley
Dimensions l1 × b1 × m2 (mm)	810 × 1210 × 235
Load dimension b9 × l3 (mm)	800 × 1200
Min. inner entry I6.1 (mm)	> 660

 \rightarrow Stable trolley transport is ensured

ightarrow Made for high tolerances on pick-up locations

PALLET TRANSPORT



Pick-and-drop station

C-MATIC HP with adaptor plate

Characteristics	C-MATIC HP 10 EPAL1 pallet length	C-MATIC HP 10 EPAL3 pallet length
Dimensions l1 × b1 × h1 (mm)	1610 × 1134 × 325	1762 × 1235 × 235
Pallet supporting surface h11 (mm)	280	280
Load dimension I3 × b9 (mm)	1200 × 800	1200 × 1000
Max. load capacity (kg)	1000	1000

 \rightarrow Stable pallet transport is ensured via pick-and-drop station

 \rightarrow Made for pallet transport with short-side leading

AUTOMATIC CHARGING STATION

Fully automated charging

- ightarrow Designed solution includes charging station
- \rightarrow Intermediate charging possible during operating breaks
- \rightarrow Charging of several vehicles via one station
- \rightarrow Vehicle can also be charged while loaded



CHARGER

	Model		48V 40A 1.9 kW		
Basic	Plug Type		Type F (EU) or G (UK)		
cal	Dimension $b \times I \times h$	(mm)	830 × 788 × 288		
Physical	Weight	(kg)	40		
ЧЧ	Length of power line	(m)	2.5		
	Rated voltage	(V)	230		
Input	Mains fuse protection	(A)	16		
ЦП	Power	(W)	3680		
	Grid frequency	(Hz)	50/60		
Ħ	Power	(W)	1920		
Output	Voltage	(V)	48		
ō	Current	(A)	40		
Others	Ambient temperature	(°C)	+5/+30		
oth	Storage temperature	(°C)	+5/+30		

STANDARD AND OPTIONAL EQUIPMENT

	Model	C-MATIC HP 10 with loading platform	C-MATIC HP 10 with adaptor plate
tion	Intelligent routing algorithms	•	•
isat	Intelligent charging logic	•	•
Digitalisation	Standard interfaces to existing WMS, ERP, etc.	0	0
	Standard interfaces with infrastructure: doors, conveyors, etc.	0	0
Safety	Control buttons (On, Off, Reset)	•	•
	Personal safety around the robot with two diagonal safety scanners	•	•
	Safety field switch between platform raised and lowered	•	•
	Two diagonally positioned emergency stops	•	•
	Audio-communication	•	•
	Robot status light	•	•
քւ	Direction indicators when turning	•	•
Lighting	BlueSpot in front and rear direction	•	•
Ē	Indirect blue line on floor	•	•
	Multi-colour status column at the rear of the robot	0	0
_	Load pick-up with high tolerances for manual positioning on marked floor	•	_
Load Handling	Natural feature navigation based on SLAM technology	٠	
pue	Camera-based load recognition		_
₽́Ħ p	Longside leading trolley transport with load dimensions of 1200 × 800 mm	•	—
Loa	Trolley transport with customised load dimensions <1600 × 1600 mm	0	_
	Short-side leading pallet transport with EPAL1 and EPAL3 pallets	-	•
on- nt	Wifi communication	٠	•
Environ- ment	Ambient temperature +5/+40°C	•	•
	Li-ION battery	•	•
Energy	Automatic opportunity charging connectors	•	•
Ene	Automatic charging station	0	0
	Energy charging status information based on flashlights in each corner	٠	•
a	Plug for remote hand control unit	•	•
Service	Hand control unit	0	0
Se	Can be transported on ISO forks	•	•
ing	Differential drive with dual forward wheel drive	٠	٠
Driving	High performance obstacle avoidance feature	٠	•

• Standard equipment O Optional equipment – Not available

CHARACTERISTICS



Safety around the vehicle



Flexible load handling



Easy access to main components



Focus on customer processes as standard

Safety

- \rightarrow Laser scanner for reliable detection of the complete vehicle environment
- \rightarrow Immediate reaction to people, vehicles or obstacles to avoid collisions
- $\rightarrow\,$ Stable load pick-up when transporting pallets and rolling racks for safe transport of goods
- \rightarrow Ideal combination of flexibility, productivity and maximum safety
- → Emergency stop switch on both sides for additional protection in everyday warehouse life

Handling

- \rightarrow Infrastructure-free SLAM technology for optimum use in automated mixed operation
- ightarrow Independent bypassing of obstacles for stable and trouble-free material flow
- \rightarrow High tolerance load pick-up for reliable transport of pallets and roller racks
- → Cloud-based control software for fast implementation and effortless vehicle management
- \rightarrow Powerful Li-ION battery and self-charging function for 24/7 operation

Service

- → Robust technology and low maintenance requirements for maximum availability
- \rightarrow Easily accessible components for rapid maintenance
- \rightarrow Fault diagnosis via service laptop or remote maintenance function for low service costs
- \rightarrow Extensive Linde MH service network for repairs and maintenance around the clock

Sales and realisation

- → Project-specific concept design including dynamic simulation and proof of concept on site if necessary
- → Combination of manual handling processes and degree of automation can be optimised to fit the customer needs
- \rightarrow One face to the customer for the whole process from first contact to the lifecycle phase
- \rightarrow Intelligent, scalable software solutions to provide customers best control of their processes
- \rightarrow Project management and commissioning according to Linde MH standards with unified tools and templates in the entire network

Presented by:

Subject to modification in the interest of progress. Illustrations and technical details could include options and are not binding for actual constructions. All dimensions subject to usual tolerances.



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